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**FINAL REPORT WORKLOAD DISTRIBUTION**

Front Page: Caner Potur

Executive summary :

Intro:

Design Description:

* Top-down system descriptions :
* Technical Specifications of Video Transfer Subsystem
* Technical Specifications of Command Transmission Subsystem
* Technical Specifications of Motor Drive Subsystem
* Technical Specifications of Shooting Subsystem
* Technical Specifications of Power Supply Subsystem

RESULTS AND ANALYSES OF PERFORMANCE TESTS:

-Range performance : Video+command

- Speed/stability of robot movements

-Shooting performance

-Power consumption

List of deliverables:

-User manual : MUST

Budget:

Conclusion:

Appendices