05.05.2019

**FINAL REPORT WORKLOAD DISTRIBUTION**

Front Page: **Caner Potur**

Executive summary: **Ercan OKATAN**

Introduction: **Mert Kayış**

Design Description:

* Top-down system descriptions: **Kagan Ozaslan**
* Technical Specifications of Video Transfer Subsystem: **Kagan Ozaslan**
* Technical Specifications of Command Transmission Subsystem: **Kagan Ozaslan**
* Technical Specifications of Motor Drive Subsystem : **Caner Potur**
* Technical Specifications of Shooting Subsystem: **Ercan OKATAN**
* Technical Specifications of Power Supply Subsystem : **Mert Kayış**

RESULTS AND ANALYSES OF PERFORMANCE TESTS:

* Range performance: Video + command: **Ercan OKATAN - Hasan ÖZKARA**
* Speed/stability of robot movements: **Hasan ÖZKARA - Mert Kayış**
* Shooting performance: **Ercan OKATAN - Hasan ÖZKARA**
* Power consumption: **Mert Kayış – Caner Potur**

List of deliverables: **Caner Potur**

Budget: **Kagan Özaslan**

Conclusion: **Mert Kayış**

Appendices

-User manual: **Caner Potur**

**-**Technical Drawings and Pictures

**Report Specifications:**

* Calibri 11 punto
* Titles are” **Bold**” Calibri 15 punto
* Figure and Table captions 10 punto and italic: *Fig. x. and Table x.*