05.05.2019

**FINAL REPORT WORKLOAD DISTRIBUTION**

Front Page: Caner Potur

Executive summary : Ercan OKATAN

Introduction: Mert Kayış

Design Description:

* Top-down system descriptions :
* Technical Specifications of Video Transfer Subsystem
* Technical Specifications of Command Transmission Subsystem
* Technical Specifications of Motor Drive Subsystem : Caner Potur
* Technical Specifications of Shooting Subsystem
* Technical Specifications of Power Supply Subsystem : Mert Kayış

RESULTS AND ANALYSES OF PERFORMANCE TESTS:

-Range performance : Video+command

- Speed/stability of robot movements

-Shooting performance

-Power consumption

List of deliverables:

-User manual : MUST

Budget:

Conclusion:

Appendices